

Substitute for Form 1449 A & B/PTO				Complete if Known	
INFORMATION DISCLOSURE STATEMENT BY APPLICANT <i>(use as many sheets as necessary)</i>				Application Number	104468756
				Confirmation Number	Not Yet Assigned
				Filing Date	February 21, 2006
				First Named Inventor	Yoshiyuki SANKAI
				Art Unit	Not Yet Assigned
				Examiner Name	Not Yet Assigned
Sheet 1 of 1				Attorney Docket Number	Q93366

U.S. PATENT DOCUMENTS					
Examiner Initials ^a	Cite No. ¹	Document Number		Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document
		Number	Kind Code ² (if known)		
		US			
		US			
		US			
		US			

FOREIGN PATENT DOCUMENTS							
Examiner Initials ^a	Cite No. ¹	Foreign Patent Document			Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Translation ⁴
		Country Code ³	Number ⁴	Kind Code ⁵ (if known)			
		JP	61-34340	B2	08-07-1986	SAKAI IRYO KABUSHIKI KAISHA	
		JP	7-163607	A	06-27-1995	TOKYO R & D CO., LTD.	Abstract
		JP	2000-166997	A	06-20-2000	NSK LTD.	Abstract
		JP	2003-79684	A	03-18-2003	HONDA MOTOR CO., LTD.	Abstract
		JP	2003-116893	A	04-22-2003	HONDA MOTOR CO., LTD.	Abstract
		JP	2-298479	A	12-10-1990	NIPPON TELEGRAPH AND TELEPHONE CORP.	Abstract

NON PATENT LITERATURE DOCUMENTS				
Examiner Initials ^a	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city, and/or country where published.	Translation ⁴	
		Takao Nakai, et al. "DEVELOPMENT OF POWER ASSISTIVE LEG FOR WALKING AID USING EMG AND LINUX," Second Asian Symposium on Industrial Automation and Robotics, BITECH, Bangkok, Thailand, May 17-18, 2001.		
		Kota Kasaoka, et al. "PREDICTIVE CONTROL ESTIMATING OPERATOR'S INTENTION FOR STEPPING-UP MOTION BY EXO-SKELETON TYPE POWER ASSIST SYSTEM HAL," Proceedings of the 2001 IEEE/RSJ International Conference on Intelligent Robots and Systems, Maui, Hawaii, USA, Oct. 29 - Nov. 3, 2001.		
		Suwoong Lee, et al. "POWER ASSIST CONTROL FOR WALKING AID BY HAL BASED ON PHASE SEQUENCE AND EMG," the collection (2001) of academic lecture meeting drafts of the 19 th Robotics Society of Japan.		

Examiner Signature	/Danton DeMille/ (10/30/2009)	Date Considered
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ALL REFERENCES CONSIDERED EXCEPT WHERE LINED THROUGH. /DD/

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¹Applicant's unique citation designation number (optional). ²See Kind Codes of USPTO Patent Documents at www.uspto.gov, MPEP 901.04 or in the comment box of this document. ³Enter Office that issued the document, by the two-letter code (WIPO Standard ST. 3). ⁴For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document. ⁵Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST. 16 if possible. ⁶Applicant is to indicate here if English language Translation is attached.